# Isolating Sources of Disentanglement in Variational Autoencoders



# Tian Qi Chen, Xuechen Li, Roger Grosse, David Duvenaud

University of Toronto. Vector Institute.



#### CONTRIBUTIONS

Variational autoencoders naturally discover disentangled representations. To understand this behavior, we explore a **refined decomposition of the KL regularization term in VAEs**.

We can amplify the source of disentanglement in VAEs which results in an **improved algo- rithm with the same number of hyperparam- eters** as the  $\beta$ -VAE. We call it  $\beta$ -TCVAE.

Quantifying disentanglement is hard, and existing approaches are mostly *ad hoc*. We design a **new measure rooted in information theory**.

#### BACKGROUND

The penalized VAE objective can be written using the evidence lower bound (ELBO):

$$\frac{1}{N} \sum_{n=1}^{N} \left[ \mathbb{E}_q[\log p(x_n|z)] - \beta \mathbf{D_{KL}} \left( q(z|x_n) || p(z) \right) \right]$$

- $\cdot \beta = 1 \longrightarrow$ Standard VAE objective.
- $\cdot \beta > 1 \longrightarrow \beta$ -VAE [1] for disentangling. Reliable in practice but not explicitly analyzed.

#### NOTION OF DISENTANGLEMENT

Each dimension of a disentangled representation should:

- (1) Represent a different factor of variation in the data.
- (2) Be able to be changed independently of the other dimensions.

It is conjectured the following may be important:

- (1) Mutual information between the latent variables and the data.
- (2) Independence between the latent variables.

$$p(n)=1/N$$
 
$$q(z)=\sum\limits_{i=1}^N p(n)q(z|n)$$
 
$$q(z,n)=q(z|n)p(n)$$

#### ELBO TC-DECOMPOSITION

$$\mathbb{E}_{p(n)}\left[\mathbf{D}_{\mathrm{KL}}\left(q(z|n)||p(z)\right)\right] = \underbrace{\mathbf{D}_{\mathrm{KL}}\!\!\left[q(z,n)||q(z)p(n)\right]}_{\text{i}} + \underbrace{\mathbf{D}_{\mathrm{KL}}\!\!\left[q(z)||\frac{\Pi}{j}q(z_j)\right]}_{\text{ii}} + \underbrace{\frac{\Sigma}{j}\mathbf{D}_{\mathrm{KL}}\!\!\left[q(z_j)||p(z_j)\right]}_{\text{iii}} \text{ Total Correlation} + \underbrace{\frac{\Sigma}{j}\mathbf{D}_{\mathrm{KL}}\!\!\left[q(z_j)||p(z_j)\right]}_{\text{iii}} + \underbrace{\frac{\Sigma}{j}\mathbf{D}_{\mathrm{KL}}\!\!\left[q(z_j)||p(z_j)\right]}$$

#### DECOMPOSITION BREAKDOWN

The ELBO objective decreases all three terms:

- i Mutual information between the training data and the latent variables [2].
- Total correlation (TC) between the latent variables. A measure of statistical dependence.
- Dimension-wise KL. Simple regularization acting on each dimension of the representation.

#### MINIBATCH-BASED ESTIMATION

We can train with arbitrary weights on each term if we can stochastically estimate  $\log q(z)$  and  $\log q(z_j)$ .

**Problem.** Evaluation of q(z) depends on full data. **Solution.** Estimate q(z) based on the current minibatch, and *weight appropriately*. Inspired by importance sampling.

$$\mathbb{E}_{q(z)}[\log q(z)] \approx \frac{1}{M} \sum_{i=1}^{M} \left[ \log \frac{1}{NM} \sum_{j=1}^{M} q(z(n_i)|n_j) \right]$$
 where  $z(n_i)$  is a sample from  $q(z|n_i)$ 

### SPECIAL CASE: $\beta$ -TCVAE

We designate a special case of the decomposition as a meaningful algorithm for learning disentangled representations, the  $\beta$ -TCVAE objective:

$$\frac{1}{N} \sum_{n=1}^{N} \left( \mathbb{E}_{q(z|n)}[\log p(n|z)] \right) - \underbrace{\mathbf{i}} - \boldsymbol{\beta} \underbrace{\mathbf{ii}} - \underbrace{\mathbf{iii}}$$

With  $\beta > 1$ , this should encourage the representation to more disentangled while preserving information about the data.

Preliminary experiments indicate that tuning the weights on either i or iii do not have as much of an effect for learning disentangled representations.

#### MEASURING DISENTANGLEMENT

If we have a set of latent variables  $\{z_j\}$  and set of known factors  $\{v_k\}$ , then we can use the empirical mutual information  $I_n(z_j; v_k)$  to quantize how well a latent variable  $z_j$  reflects a ground truth factor  $v_k$ . The full metric we call **mutual information gap** (MIG) is

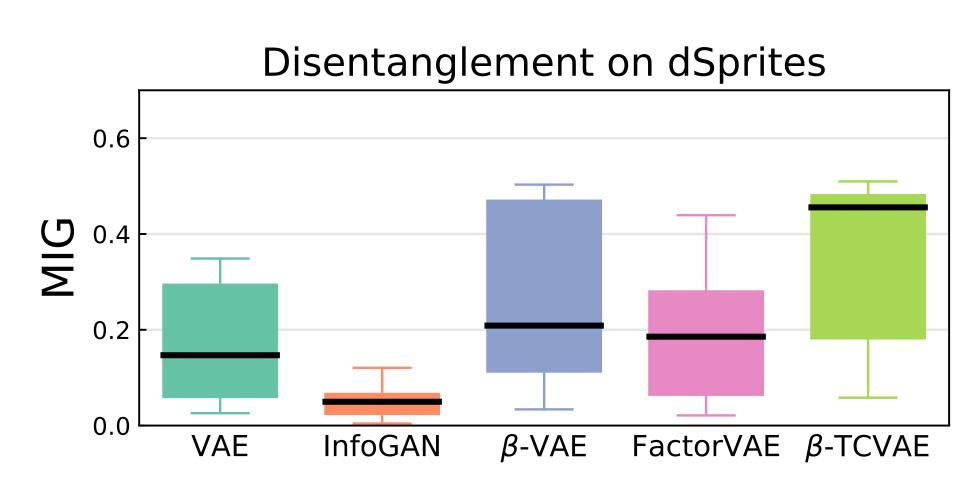
$$\frac{1}{K} \sum_{k=1}^{K} \frac{1}{H(v_k)} \left( I_n(z_{j^{(k)}}; v_k) - \max_{j \neq j^{(k)}} I_n(z_j; v_k) \right) \tag{1}$$

where  $j^{(k)} = \operatorname{argmax}_{j} I_{n}(z_{j}; v_{k})$  and K is the number of known factors.

The gap encourages two important properties:

- Axis-alignment of the representation.
- Compactness of the representation.

### QUANTITATIVE COMPARISONS



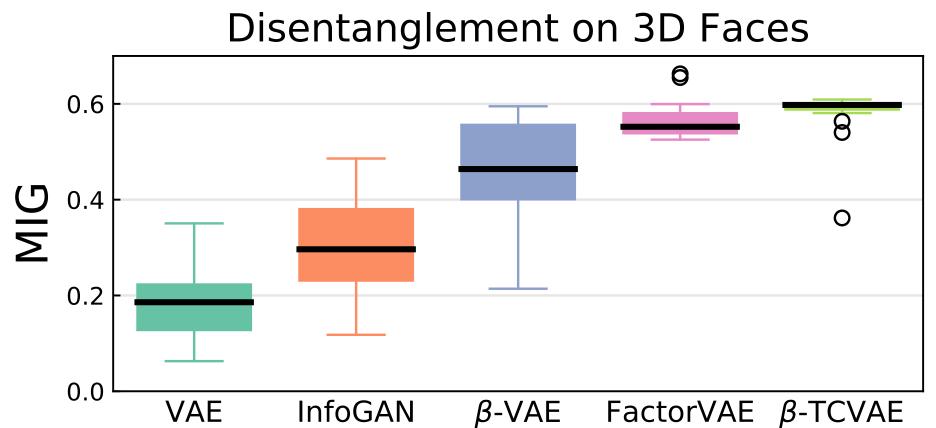


Figure: Distribution of disentanglement score (MIG) for representation learning algorithms.

# DISENTANGLED VS. INDEPENDENT REPRESENTATIONS

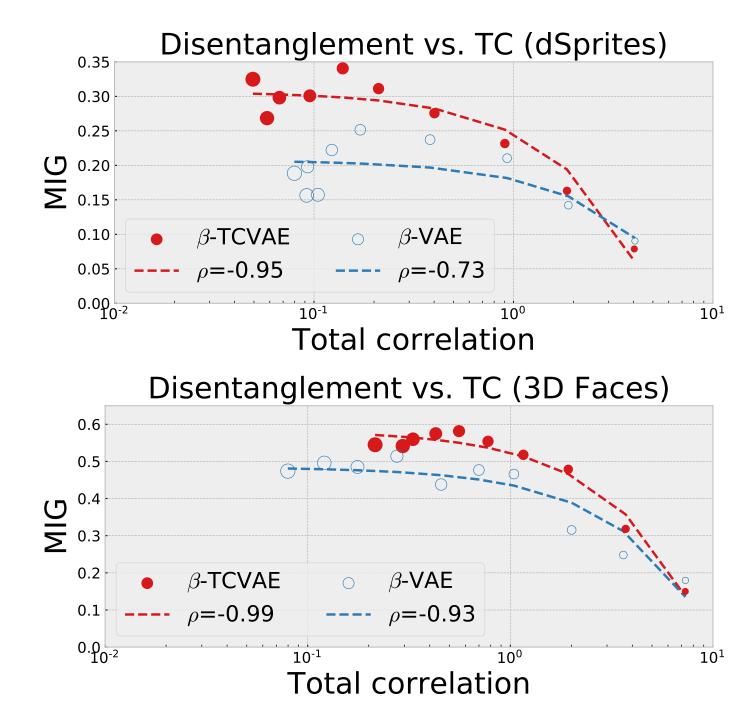
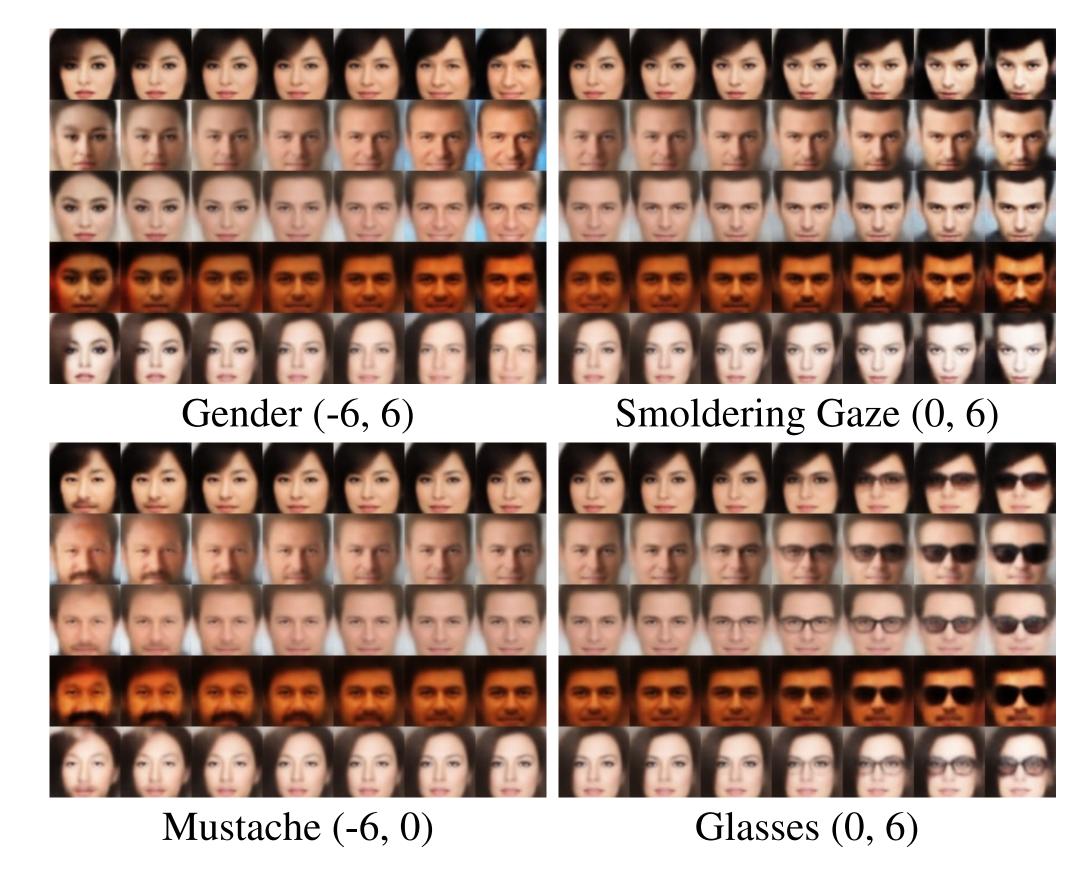


Figure: Scatter plots of the average MIG and TC per value of  $\beta$ . Larger circles indicate a higher  $\beta$ .

## QUALITATIVE RESULTS



#### REFERENCES

- [1] Higgins et al. (2017). Beta-VAE.
- 2] Hoffman & Johnson (2017). ELBO Surgery.
- Kim & Mnih (2018). Disentangling by Factorising.
- Achille & Soatto (2017). *Information Dropout*.