

Spatio-Temporal Event Modeling

Towards building a **generative model** of *discrete events* that are localized in continuous time and space. Each sample is a sequence of **variable** length (e.g. all events within $t_i \in [0, T]$):

$$\mathcal{H} = \{(t_1, \mathbf{x}_1), (t_2, \mathbf{x}_2), \dots\}$$

Applications include spatial propagation of neurons, epidemic outbreaks, ride-hailing customers, earthquakes, etc.

Events can propagate along complex routes, requiring *high-fidelity conditional spatial distributions*.

Point Processes

Characterized by a conditional intensity function $\lambda(t, \mathbf{x} | \mathcal{H}_t) \triangleq$

$$\lim_{\Delta t \downarrow 0, \Delta \mathbf{x} \downarrow 0} \frac{\mathbb{P}(\text{One event occurs in } [t, t + \Delta t], B(\mathbf{x}, \Delta \mathbf{x}) | \mathcal{H}_t)}{|B(\mathbf{x}, \Delta \mathbf{x})| \Delta t}$$

where \mathcal{H}_t denotes history before time t , and $B(\mathbf{x}, \Delta \mathbf{x})$ denotes a ball centered at $\mathbf{x} \in \mathbb{R}^d$ and with radius $\Delta \mathbf{x}$.

Maximum likelihood training requires solving an integral in \mathbf{x} ,

$$\log p(\mathcal{H}) = \sum_{i=1}^n \log \lambda^*(t_i, \mathbf{x}_i) - \int_0^T \int_{\mathbb{R}^d} \lambda^*(\tau, \mathbf{x}) d\mathbf{x} d\tau.$$

Continuous Normalizing Flows (CNF)

Describes a **continuum of distributions** by tracking *infinitesimal* changes. Given $\frac{d\mathbf{x}_t}{dt} = f_\theta(t, \mathbf{x})$, the time-dependent distribution follows

$$\log p_t(\mathbf{x}_t) = \log p_0(\mathbf{x}_0) - \int_0^t \nabla \cdot f dt$$

The resulting probability densities p_t are tractable to compute (with an ODE solver) and **always normalized**.

Neural Spatio-Temporal Point Process

Parameterize intensity with density of a CNF.

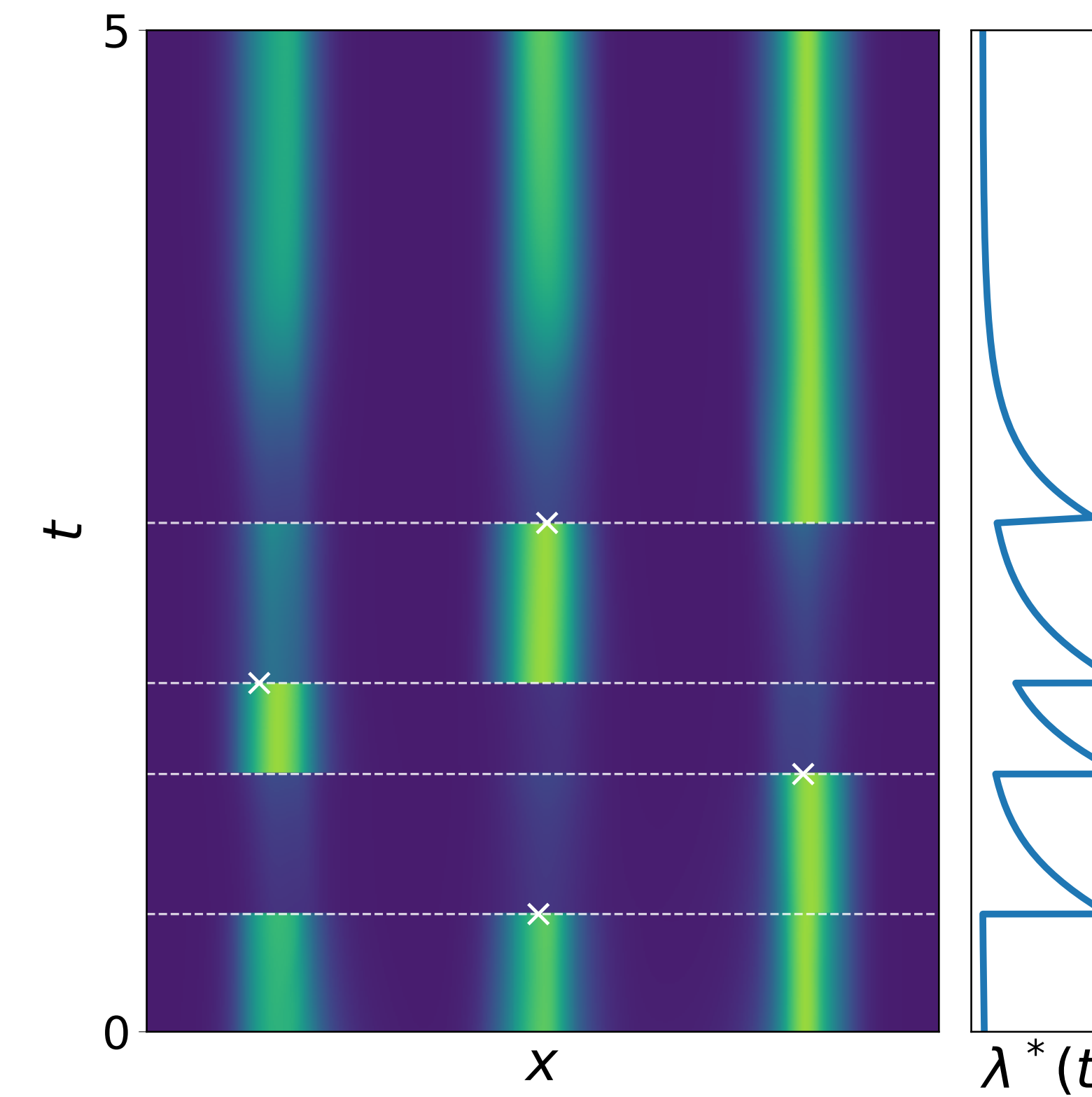
$$\lambda^*(t, \mathbf{x}) = \lambda^*(t) p^*(\mathbf{x} | t)$$

where $*$ is shorthand for dependence on history \mathcal{H}_t .

(Effectively replaces $\int_{\mathbb{R}^d}$ with $n \int_0^{t_i}$)

$$\log p(\mathcal{H}) = \sum_{i=1}^n \log \lambda^*(t_i) - \int_0^T \lambda^*(\tau) d\tau + \sum_{i=1}^n \log p^*(\mathbf{x}_{t_i} | t_i)$$

How can we **condition a CNF** on \mathcal{H}_t for parameterizing p^* ?



Instantaneous vs. Continuous Updates

Jump CNF: Models conditioning with instantaneous *jumps* using standard normalizing flows.

Slow: requires sequentially updating for each event in \mathcal{H}_t .

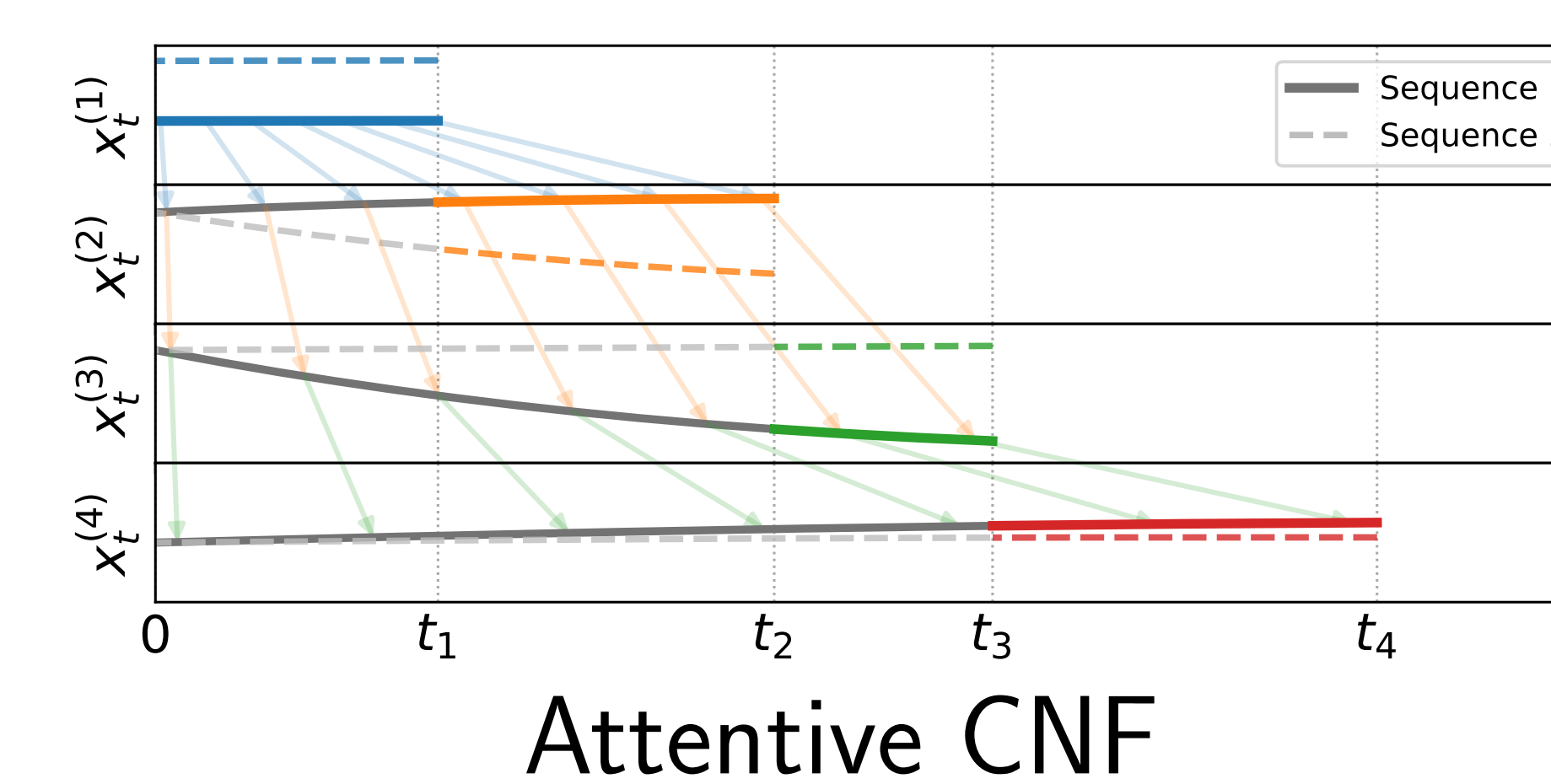
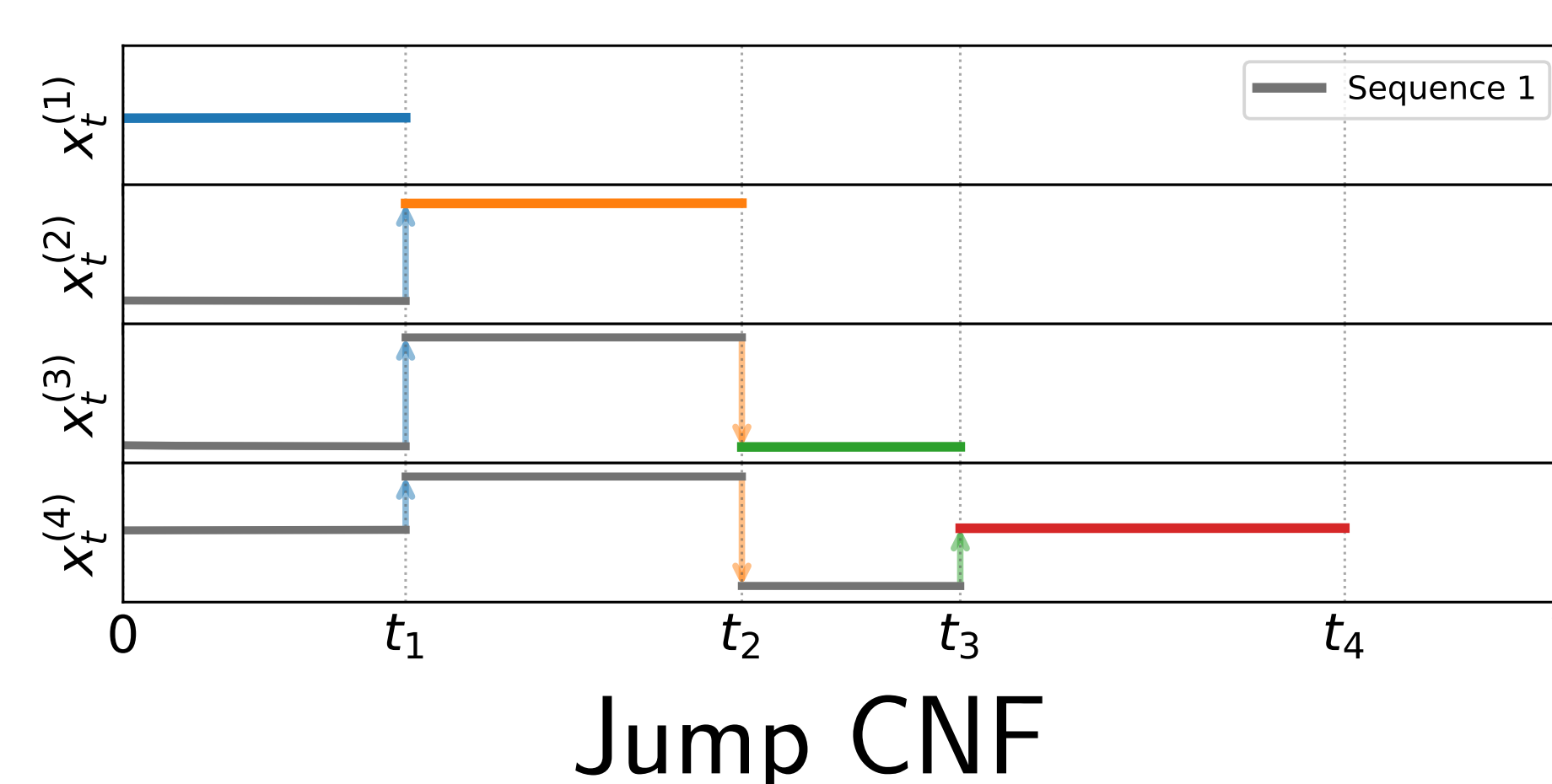
Attentive CNF: Models conditioning with *continuous attention* on the sample paths within the drift function f .

$$\frac{d\{\mathbf{x}_i\}_{i=0}^n}{dt} = f(\mathbf{x}_1, \dots, \mathbf{x}_n) = \text{MaskedMultiheadAttention}$$

Fast: all ODEs can be solved in parallel.

Low-variance: Structure within MultiheadAttention allows efficient low-variance estimator of $\nabla \cdot f$.

Sample paths for a sequence of events:



Ablation Experiments

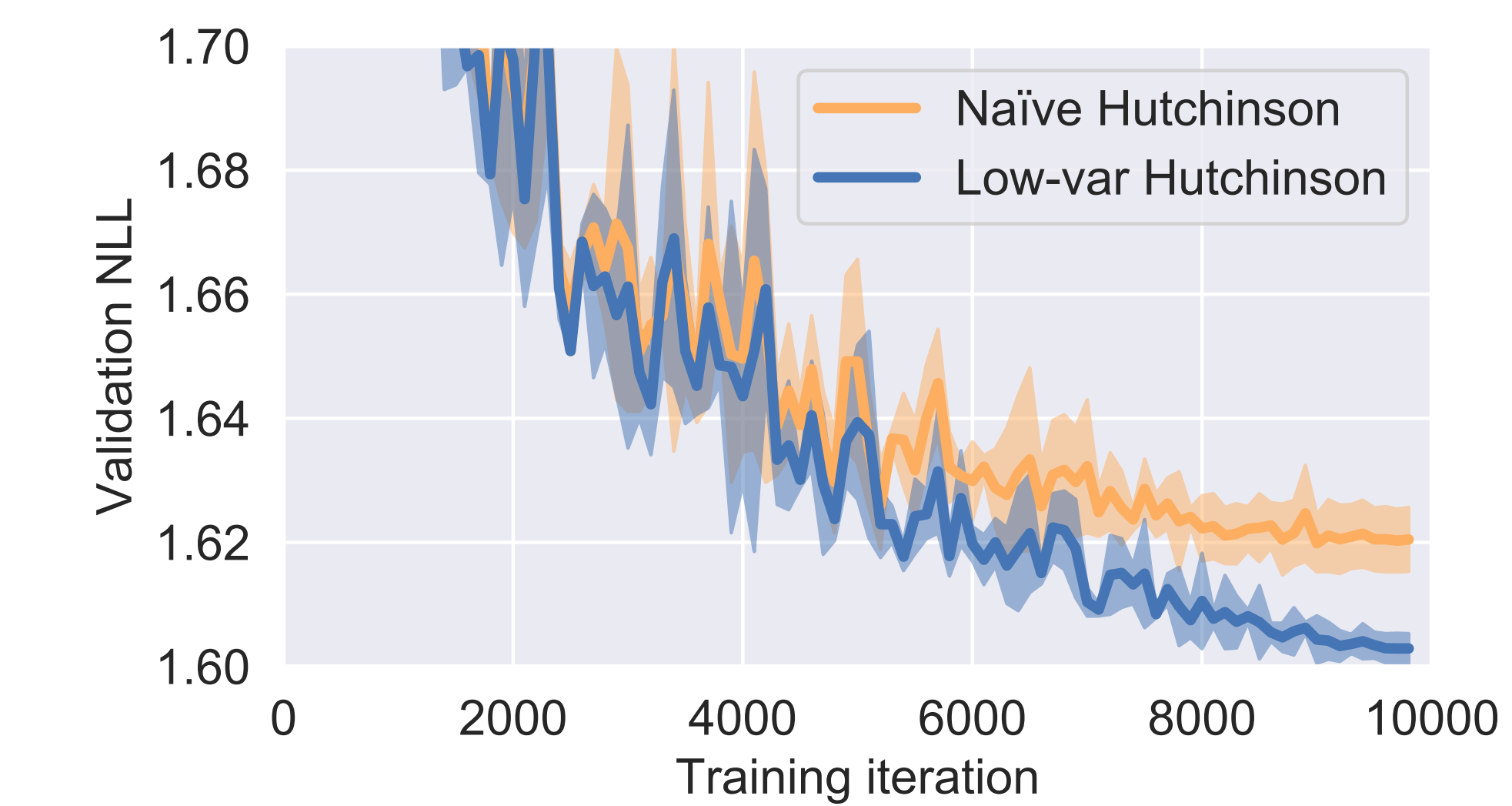


Figure: Low-variance Estimator

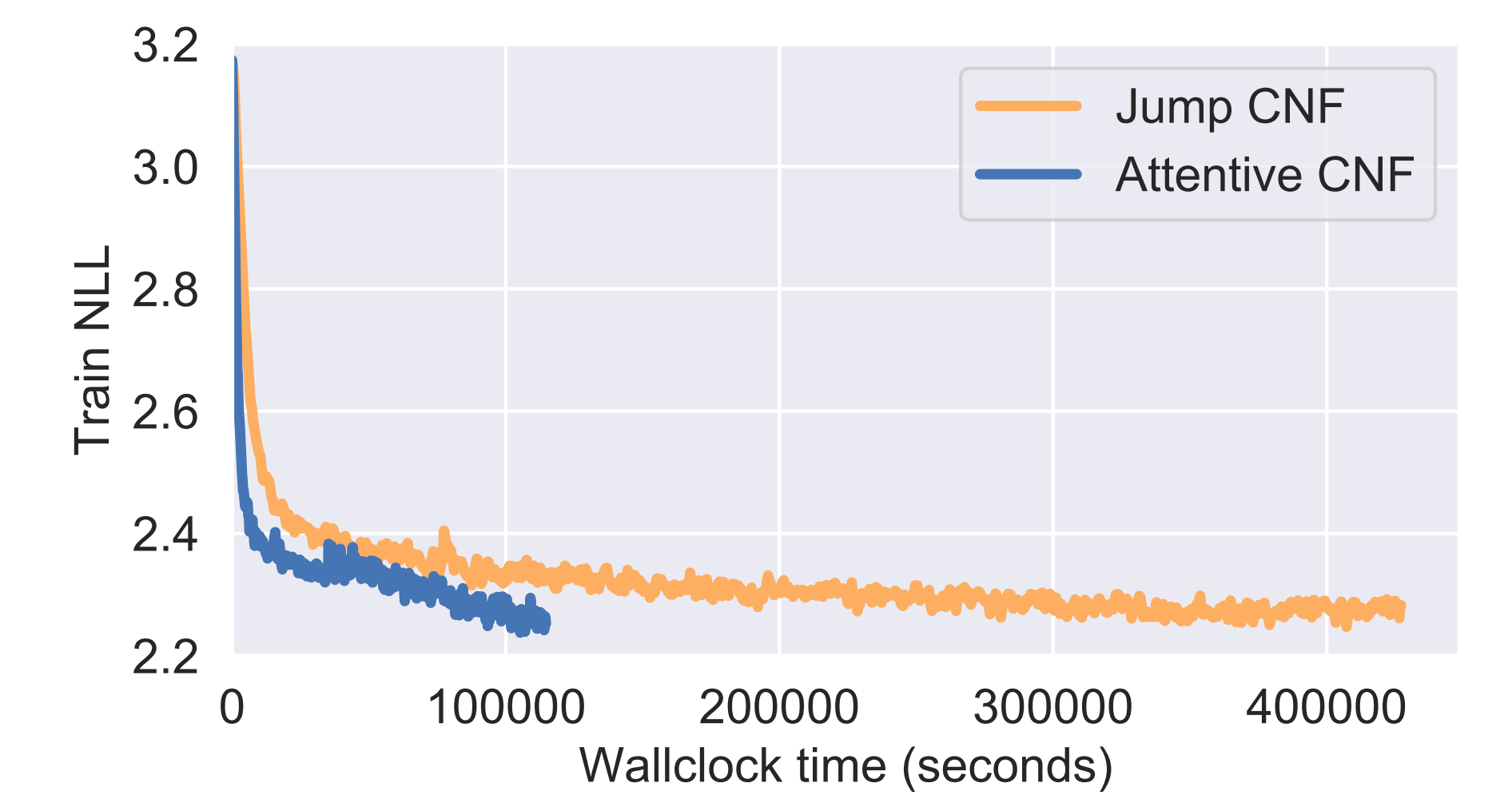


Figure: Runtime Comparison

Applications across Multiple Domains

| Model | Pinwheel | | Earthquakes JP | | COVID-19 NJ | | BOLD5000 | |
|-------------------------|--------------------|--------------------|--------------------|--------------------|---------------------|--------------------|--------------------|--------------------|
| | Temporal | Spatial | Temporal | Spatial | Temporal | Spatial | Temporal | Spatial |
| Poisson Process | -0.784 \pm 0.001 | - | -0.111 \pm 0.001 | - | 0.878 \pm 0.016 | - | 0.862 \pm 0.018 | - |
| Self-correcting Process | -2.117 \pm 0.222 | - | -7.051 \pm 0.780 | - | -10.053 \pm 1.150 | - | -6.470 \pm 0.827 | - |
| Hawkes Process | -0.276 \pm 0.033 | - | 0.114 \pm 0.005 | - | 2.092 \pm 0.023 | - | 2.860 \pm 0.050 | - |
| Neural Hawkes Process | -0.023 \pm 0.001 | - | 0.198 \pm 0.001 | - | 2.229 \pm 0.013 | - | 3.080 \pm 0.019 | - |
| Conditional KDE | - | -2.958 \pm 0.000 | - | -2.259 \pm 0.001 | - | -2.583 \pm 0.000 | - | -3.467 \pm 0.000 |
| Time-varying CNF | - | -2.185 \pm 0.003 | - | -1.459 \pm 0.016 | - | -2.002 \pm 0.002 | - | -1.846 \pm 0.019 |
| Neural Jump SDE (GRU) | -0.006 \pm 0.042 | -2.077 \pm 0.026 | 0.186 \pm 0.005 | -1.652 \pm 0.012 | 2.251 \pm 0.004 | -2.214 \pm 0.005 | 5.675 \pm 0.003 | 0.743 \pm 0.089 |
| Jump CNF | 0.027 \pm 0.002 | -1.562 \pm 0.015 | 0.166 \pm 0.001 | -1.007 \pm 0.050 | 2.242 \pm 0.002 | -1.904 \pm 0.004 | 5.536 \pm 0.016 | 1.246 \pm 0.185 |
| Attentive CNF | 0.034 \pm 0.001 | -1.572 \pm 0.002 | 0.204 \pm 0.001 | -1.237 \pm 0.075 | 2.258 \pm 0.002 | -1.864 \pm 0.001 | 5.842 \pm 0.005 | 1.252 \pm 0.026 |

Table: Log-likelihood per event on held-out test data (higher is better).

Adapts Spatial Densities On-the-fly

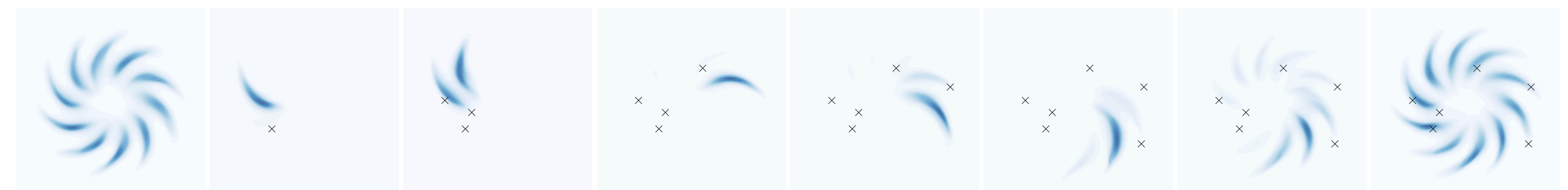


Figure: Evolution of spatial densities before returning back to marginal density.

Useful References and Links

- [1] "Neural Ordinary Differential Equations" Chen et al. (2018)
- [2] "FFJORD: <abbreviated>" Grathwohl & Chen et al. (2019)
- [3] "Neural Jump SDEs" Jia & Benson (2019)
- [4] "The Lipschitz Constant of Self-Attention" Kim et al. (2020)

Code: https://github.com/facebookresearch/neural_stpp